

November 28 (Mon.)

Opening Remarks

Room 1

Chairperson: *Fumihito Arai, The University of Tokyo*

9:00-9:20 *Prof. Toshio Fukuda, Nagoya University (Honorary Chair)*
Prof. Fumihito Arai, The University of Tokyo (General Co-Chair)
Prof. Koichi Suzumori, Tokyo Institute of Technology (General Co-Chair)
Prof. Jun Ota, The University of Tokyo (General Co-Chair)

Plenary Talks

Room 1

Chairperson: *Koichi Suzumori, Tokyo Institute of Technology*

9:20-10:05 **Plenary Talk 1**
Molecular Robotics based on Soft Matter Physics of DNA[PL1](#)
Masahiro Takinoue^{1, 2}
¹*Department of Computer Science, Tokyo Institute of Technology*
²*Living Systems Materialogy Research Group, International Research Frontiers Initiative, Tokyo Institute of Technology*

10:05-10:20 **Break**

Session MA1-1: (Organized Session 10-1): Science of Soft Robots

Room 1

Chairperson: *Kohei Nakajima, The University of Tokyo*
Shingo Maeda, Tokyo Institute of Technology

10:20-10:50 **Keynote Talk 10-1**
Self-Modifying Bio-Soft Robots[MA1_1_1](#)
Masahiro Shimizu
Graduate School of Engineering Science, Osaka University

10:50-11:20 **Keynote Talk 10-2**
Self-excited Actuation for soft robots[MA1_1_2](#)
Hiroyuki Nabae
Tokyo Institute of Technology

11:20-11:50 **Keynote Talk 10-3**
Bio-inspired Flight with Soft Mechanism[MA1_1_3](#)
Toshiyuki Nakata
Chiba University

- 11:50-12:05 Pre-training on physical dynamics enhances indirect sensing in recurrent neural networks [MA1_1_4](#)
Mitsuhiro Nishida¹, Ryo Sakurai¹, Yasumichi Wakao¹, and Kohei Nakajima²
¹*Bridgestone Corporation*
²*The University of Tokyo*
- 12:05-12:20 Implementation of Reservoir Computing Algorithm in Stretchable Sensor for Wearable Device [MA1_1_5](#)
W. Thongking¹, A. Wiranata^{2,3}, S. Maeda⁴ and C. Premachandra¹
¹*Department of Electronic Engineering, Shibaura Institute of Technology*
²*Department of Engineering and Science, Shibaura Institute of Technology*
³*Department of Mechanical and Industrial Engineering, University of Gadjah Mada*
⁴*Department of Mechanical Engineering, Tokyo Institute of Technology*

Session MA2-1: (Organized Session 5)
Hyper-Adaptability

Room 2

Chairperson: *Toshiyuki Kondo, Tokyo University of Agriculture and Technology*

- 10:20-10:35 Investigation of a Method to Extend a 2-Dimensional Gait to 3-Dimensions in a Human Musculoskeletal Model with 70 Muscles [MA2_1_1](#)
Hitohiro Etoh¹, Yuichiro Omura¹, Kohei Kaminishi², Ryosuke Chiba³, Kaoru Takakusaki³ and Jun Ota²
¹*Department of Precision Engineering, Graduate School of Engineering, The University of Tokyo*
²*Research into Artifacts, Center for Engineering, Graduate School of Engineering, The University of Tokyo*
³*Division on Neuroscience, Department of Physiology, School of Medicine, Asahikawa Medical University*
- 10:35-10:50 Muscle Tone in a Musculoskeletal Model to Represent the Abnormal Posture in Parkinson's Disease [MA2_1_2](#)
Yuichiro Omura¹, Hiroki Togo², Kohei Kaminishi³, Tetsuya Hasegawa¹, Ryosuke Chiba⁴, Arito Yozu¹, Kaoru Takakusaki⁴, Mitsunari Abe⁵, Yuji Takahashi⁵, Takashi Hanakawa², and Jun Ota³
¹*Graduate School of Engineering, The University of Tokyo*
²*Graduate School of Medicine and Faculty of Medicine Kyoto University*
³*Research into Artifacts, Center for Engineering (RACE), School of Engineering, The University of Tokyo*
⁴*Division on Neuroscience, Department of Physiology, Asahikawa Medical University*
⁵*National Center of Neurology and Psychiatry*

- 10:50-11:05 Effects of plantar pain on gait [MA2_1_3](#)
*Kohta Sonoda¹, Tetsuya Hasegawa¹, Kohei Kaminishi¹, Michihiro Osumi²,
Masahiko Sumitani³, Ryosuke Chiba⁴, Jun Ota¹, and Arito Yozu¹*
¹*Department of Precision Engineering, School of Engineering, The University of Tokyo*
²*Department of Neurorehabilitation, Graduate School of Health Sciences, Kio University*
³*Department of Pain and Palliative Medicine, The University of Tokyo Hospital*
⁴*Division on Neuroscience, Department of Physiology, Asahikawa Medical University*
- 11:05-11:20 Ring-shaped wearable device for logging finger usage in daily life [MA2_1_4](#)
Naoya Yamamoto, Takato Matsumoto, Tamami Sudo, Megumi Miyashita, and Toshiyuki Kondo
Department of Computer and Information Sciences, Graduate School of Engineering, Tokyo University of Agriculture and Technology
- 11:20-11:35 Transfer of Partial Information of Motor Controller Based on Estimation of Coordinate Transformation Parameters [MA2_1_5](#)
Yuichi Kobayashi and Sota Nakamura
Shizuoka University
- 11:35-11:50 Selective instance segmentation by using Mutual loss [MA2_1_6](#)
Noritaka Hiiro and Tsuyoshi Tasaki
Graduate School of Science and Technology, Meijo University
- 11:50-12:05 Keynote Talk 5-1
Motor synergy generalization framework for new targets in multi-planar and multi-directional reaching task [MA2_1_7](#)
Kyo Kutsuzawa and Mitsuhiro Hayashibe
Graduate School of Engineering, Tohoku University
- 12:05-12:20 Keynote Talk 5-2
A condition on exploration noise during De Novo motor learning that is driven by sensory prediction error [MA2_1_8](#)
Jun Izawa
University of Tsukuba
- 12:20-13:20 **Lunch**

Plenary Talks

Room 1

Chairperson: *Toshiyuki Kondo, Tokyo University of Agriculture and Technology*

13:20-14:05 Plenary Talk 2
Experimental and computational studies of bipedal locomotion in the Japanese macaque towards understanding the evolution of human bipedal locomotion [PL2](#)
Naomichi Ogiwara
Department of Biological Sciences, Graduate School of Science, University of Tokyo

14:05-14:20 **Break**

Session MP1-1: (Organized Session 10-2)

Science of Soft Robots

Room 1

Chairperson: *Ryuma Niiyama, Meiji University*
Hiroyuki Nabae, Tokyo Institute of Technology

14:20-14:50 Keynote Talk 10-4
Do Soft Robots Dream of Florence Nightingale? [MP1_1_1](#)
Shoko Miyagawa
Keio University

14:50-15:05 Water-Pre-Stretched Dielectric Elastomer Actuator Made of an Organogel [MP1_1_2](#)
Yuta Tezuka, Asahi Tsujino, and Takeshi Hayakawa
Department of Precision Engineering, Chuo University

15:05-15:20 Open-Loop Control of Displacement of Water-Pre-Stretched Dielectric Elastomer Actuator [MP1_1_3](#)
Asahi Tsujino and Takeshi Hayakawa
Department of Precision Engineering, Chuo University

Session MP2-1: (Organized Session 3-1)

Emerging technologies for spatiotemporal analysis of cells

Room 2

Chairperson: *Shinya Sakuma, Kyushu University*
Niko Kimura, Kyushu University

14:20-14:35 High-speed On-chip In-liquid Dispenser by Utilizing Traveling Vortex [MP2_1_1](#)
Makoto Saito, Yoko Yamanishi, and Shinya Sakuma
Department of Mechanical Engineering, Kyushu University

- 14:35-14:50 A sample fixation method utilizing electroadhesion toward tensile characterization of thin and small biomembrane [MP2_1_2](#)
Kosuke Narayama, Yoko Yamanishi and Shinya Sakuma
Department of Mechanical Engineering, Kyushu University
- 14:50-15:05 Live Cell Imaging of Humoral Factor Secretion as an Indicator of Cytotoxicity in Cancer Immunity [MP2_1_3](#)
Yuto Kurisu¹, Zhuohao Yang¹, Koji Nagaoka², Kazuhiro Kakimi², Takashi Funatsu¹, and Yoshitaka Shirasaki¹
¹Graduate School of Pharmaceutical Sciences, The University of Tokyo
²Department of Immunotherapeutics, The University of Tokyo Hospital
- 15:05-15:35 Keynote Talk 3-1
 Cellular senescence in age-related diseases [MP2_1_4](#)
Akiko Takahashi
Cancer Institute
- 15:15-15:50 **Break**

Session MP1-2: (Organized Session 2)
Cognitive Robotics

Room 1

Chairpersons: *Naoyuki Kubota, Tokyo Metropolitan University*

- 15:50-16:20 Keynote Talk 2
 Mutual Understanding in Human-robot Interaction [MP1_2_1](#)
Masayoshi Kanoh
Chukyo University
- 16:20-16:35 Heat Source Approaching by Cyborg Cockroach Using a New Antennae Electrode Implantation Method [MP1_2_2](#)
Kazuyoshi Hirao, Mochammad Ariyanto, Yoshiki Fujita, and Keisuke Morishima
Department of Mechanical Engineering, Osaka University
- 16:35-16:50 Cyborg Cockroaches can be Commanded to Play Soccer [MP1_2_3](#)
Mochammad Ariyanto, C. M. Masum Refat, Kazuyoshi Hirao, and Keisuke Morishima
Department of Mechanical Engineering, Osaka University
- 16:50-17:05 Human Body Parts Estimation Using Deep Learning for 3D Point Clouds [MP1_2_4](#)
Futoshi Kobayashi, Riku Sakurai, Yusuke Suga, and Hiroyuki Nakamoto
Graduate School of System Informatics, Kobe University

- 17:05-17:20 Feature Extraction using Topological Twin for Developing Robot Partner [MP1_2_5](#)
Chenghui Liu, Ryosuke Tanno, Kodai Kaneko, and Naoyuki Kubota
Graduate School of System Design, Tokyo Metropolitan University
- 17:20-17:35 Cosine Similarity of Convolutional Features of Video Frames as a Method for Finding Similar Activities from Past and Present Information of Video Input [MP1_2_6](#)
Franz Chuquirachi, Chyan Zheng Siow, Wei Hong Chin, and Naoyuki Kubota
Graduate School of System Design, Tokyo Metropolitan University

Session MP2-2: (Organized Session 3-2)

Emerging technologies for spatiotemporal analysis of cells

Room 2

Chairperson: *Shinya Sakuma, Kyusyu University*
Yoshitaka Shirasaki, The University of Tokyo

- 15:50-16:05 A Multi-Locational Evaluation of Viscoelasticity of Hydrogels by Using Gel Actuator [MP2_2_1](#)
Hibiki Nakajima¹, Yuha Koike¹, Yoshiyuki Yokoyama², Masaya Hagiwara³, and Takeshi Hayakawa¹
¹*Chuo University*
²*Toyama Industrial Technology Research and Development Center*
³*RIKEN*
- 16:05-16:20 Evaluation of viability of single synechocystis sp. pcc 6803 in reaction to high-speed osmotic pressure change [MP2_2_2](#)
Shingo Kaneko¹, Masaru Tsujii², Nobuyuki Uozumi², and Fumihito Arai¹
¹*Department of Mechanical Engineering, The University of Tokyo*
²*Department of Biomolecular Engineering, Tohoku University*
- 16:20-16:35 Local Deposition of Metal Nanoparticles on Hydrogels Using Micro-plasma-bubbles [MP2_2_3](#)
Haruna Takahashi, Yu Yamashita, Shinya Sakuma, and Yoko Yamanishi
Department of Mechanical Engineering, Kyushu University
- 16:35-16:50 Single-point ultra-sound microscopy for flow cytometric non-contact mechanical indexing of microparticles [MP2_2_4](#)
Yuki Goto, Yoko Yamanishi, and Shinya Sakuma
Department of Mechanical Engineering, Kyushu University
- 16:50-17:20 Keynote Talk 3-2
 Chemical Probe: Innovative Chemical Tools for Cell Analysis [MP2_2_5](#)
Kosuke Dodo
RIKEN Cluster for Pioneering Research

November 29 (Tue.)

Plenary Talks

Room 1

Chairperson: *Hisataka Maruyama, Nagoya University*

- 9:00-9:45 Plenary Talk 3
 Soft Sensors, Electronics and Robots [PL3](#)
Xinyu Liu
Department of Mechanical and Industrial Engineering, University of Toronto
- 9:45-10:00 **Break**

Session TA1-1: (Organized Session 9)

New materials and processing for micro/nano devices

Room 1

Chairperson: *Yuki Toku, Nagoya University*

- 10:00-10:30 Keynote Talk 9
 Development of MEMS Loop Heat Pipe for Wearable Interfaces
 [TA1_1_1](#)
Ai Ueno
Nagoya University
- 10:30-10:45 Size effect of raw CuO nanoparticles on femtosecond laser reductive
 sintering in ambient atmosphere [TA1_1_2](#)
Kyohei Yoshidomi and Mizue Mizoshiri
Nagaoka University of Technology
- 10:45-11:00 The effect of alloy composition on beta-relaxation of Ni-Nb-Zr thin film
 amorphous alloys [TA1_1_3](#)
Jinglan Xie, Fuyuki Haga, Chiemi Oka, Seiichi Hata, and Junpei Sakurai
Department of Micro-Nano Systems Engineering, Graduate School of Engineering, Nagoya University
- 11:00-11:15 Time-resolved observation of phenomenon of cobalt precipitation from
 glyoxylic acid cobalt complex ink using femtosecond laser pulse-induced
 reduction [TA1_1_4](#)
Kazuki Yamamoto¹, Tomoji Ohishi², and Mizue Mizoshiri¹
Department of Mechanical Engineering, Nagaoka University of Technology
Department of Applied Chemistry, Shibaura Institute of Technology

- 11:15-11:30 Microscopic integration of thermoelectrically driven variable stiffness actuator fabricated of shape memory polymer [TA1_1_5](#)
Hirotaka Sugiura¹, Satoshi Amaya¹, Jun Sawada¹, and Fumihito Arai¹
Department of Mechanical Engineering, The University of Tokyo

Session TA2-1: (Organized Session 8-1)

Micro/Nano Functional Devices for in vivo/vitro applications

Room 2

Chairpersons: *Masaru Takeuchi, Nagoya University*
Tadayoshi Aoyama, Nagoya University

- 10:00-10:15 Cyborg Insects Powered by An Insect-Mountable Biofuel Cell [TA2_1_1](#)
Tomohide Hayashi and Kan Shoji
Department of Mechanical Engineering, Nagaoka University of Technology

- 10:15-10:30 Wirelessly Powered Neurostimulator with Arbitrary AC Waveforms for High-Frequency Alternating Current Block to a Peripheral Nerve [TA2_1_2](#)
Naoki Ito¹, Masaru Takeuchi¹, Katsuhiko Tokutake², Tadayoshi Aoyama¹, Sota Saeki², Shigeru Kurimoto², Hitoshi Hirata², and Yasuhisa Hasegawa¹
¹*Department of Micro-Nano Mechanical Science and Engineering, Nagoya University*
²*Department of Human Enhancement and Hand Surgery, Nagoya University*

- 10:30-10:45 Lift-off Process of On-chip Micro-Gel Actuator for Cell Manipulations [TA2_1_3](#)
Kyoka Nakano¹, Hiroki Wada¹, Yoshiyuki Yokoyama², and Takeshi Hayakawa¹
¹*Department of Precision Engineering, Chuo University*
²*Toyama Industrial Technology Research and Development Center*

- 10:45-11:00 Evaluation of improved acoustic vibration for acoustofluidic manipulation [TA2_1_4](#)
Hayato Yamaki, Natsumi Hirata, and Takeshi Hayakawa
Department of Precision Engineering, Chuo University

- 11:00-11:15 Control Method of Fabric Actuator Suit for Gaze Guidance in Immersive Spaces [TA2_1_5](#)
Kenta Yokoe¹, Tadayoshi Aoyama¹, Yuki Funabara², Koki Nakagawa², Yusuke Sakai², Masaru Takeuchi¹ and Yasuhisa Hasegawa¹
¹Department of Micro-Nano Mechanical Science and Engineering, Nagoya University
²Department of Information and Communication Engineering, Nagoya University

11:30-13:00 **Lunch**

Session TP1-1: (Organized Session 4)

Functional Interfaces and Hydro-Electrochemical Mechatronics

Room 1

Chairperson: *Yoko Yamanishi, Kyushu University*
Shingo Maeda, Tokyo Institute of Technology

- 13:00-13:30 Keynote Talk 4
Vibration / acoustic tests with a laser technology or a soft actuator [TP1_1_1](#)
Naoki Hosoya
Shibaura Institute of Technology
- 13:30-13:45 Modeling and Analysis of Plasma-induced bubble for On-demand Metal deposition [TP1_1_2](#)
Yu Yamashita, Shinya Sakuma, and Yoko Yamanishi
Department of Mechanical Engineering, Kyushu University
- 13:45-14:00 Fabrication of a stretchable electroadhesive pad [TP1-1-3](#)
Ayato Minaminosono¹, Ryoma Toyoda¹, Naoki Hosoya¹, and Shingo Maeda²
¹Mechanical Dynamics Laboratory, Shibaura Institute of Technology
²Smart Materials and Robotics Laboratory, Tokyo Institute of Technology
- 14:00-14:15 Effect of dimethylsiloxane-co-ethylene oxide block copolymer addition into polydimethylsiloxane on the harvesting of collagen micropattern by microcasting [TP1_1_4](#)
Aifang Han, Nobuyuki Tanaka, Koki Yamamoto, and Yo Tanaka
RIKEN Center for Biosystems Dynamics Research
- 14:15-14:30 Stiffness investigation depending on wavenumber of Self-folded Corrugated Structure by analytical solution [TP1_1_5](#)
Yuki Fukatsu and Hiroki Shigemune
Department of Electrical Engineering, Shibaura Institute of Technology

Session TP2-1: (Organized Session 8-2)

Micro/Nano Functional Devices for in vivo/vitro applications

Room 2

Chairperson: Masaru Takeuchi, Nagoya University
Tadayoshi Aoyama, Nagoya University

- 13:00-13:15 Fabrication of 3D Printed Pipette Tip Integrated with Capacitive
Microsensor for Cell Manipulation [TP2_1_1](#)
Satoshi Amaya, Hirotaka Sugiura, Bilal Turan, Shingo Kaneko, and
Fumihito Arai
Department of Mechanical Engineering, The University of Tokyo
- 13:15-13:30 Micro-Scale Phase-separation Liposome Detection system of flavor
concentrations in Sake, a traditional alcoholic drink in Japan
..... [TP2_1_2](#)
Tsuyoshi Yoda^{1, 2}
¹Aomori Prefectural Industrial Technology Research Center, Hachinohe
Industrial Research Institute
²The United Graduate School of Agricultural Sciences, Iwate University
- 13:30-13:45 Evaluation of Chemotaxis with Microfluidic Devices for Cancer Detection
Using *C. elegans* [TP2_1_3](#)
Hiromasa Shiga¹, Toshio Fukuda², Masaru Takeuchi³, Eunhye Kim³,
Yasuhisa Hasegawa^{2, 3}, Kenichi Ohara¹, Takuya Ishikawa⁴, and Naoki
Hisamoto⁵
¹Department of Mechatronics Engineering, Meijo University
²Institutes of Innovation for Future Society, Nagoya University
³Department of Micro-Nano Mechanical Science and Engineering,
Nagoya University
⁴Department of Medical Science, Nagoya University
⁵Division of Biological Science Cell Regulation, Nagoya University
- 13:45-14:00 Effect of magnetic extension on bio-actuator along with consistent culture
..... [TP2_1_4](#)
Zhaoyu Wang, Taisuke Masuda, and Fumihito Arai
Department of Mechanical Engineering, The University of Tokyo
- 14:00-14:15 A Hybrid Tendon Structure Using Cell Density Gradient in Cultured Muscle
..... [TP2_1_5](#)
Takuto Nomura¹, Masaru Takeuchi¹, Eunhye Kim¹, Toshio Fukuda², and
Yasuhisa Hasegawa^{1, 2}
¹Department of Micro-Nano Mechanical Science and Engineering,
Nagoya University
²Institutes of Innovation for Future Society, Nagoya University

15:30-15:45 **Break**

Session TP1-2: (Organized Session 7)
Machine-fluid interactions in microscale

Room 1

Chairperson: Takeshi Hayakawa, Chuo University

- 14:45-15:15 Keynote Talk 7
Macro biological transports induced by micro-scale gas generation by fermenting yeast cells [TP1_2_1](#)
Kenji Kikuchi
Department of Finemechanics, Graduate School of Engineering, Tohoku University
- 15:15-15:30 Generation of Various Cell Patterns with Millimeter Scale by Applying Horizontal Vibrations [TP1_2_2](#)
Kohei Morita and Takeshi Hayakawa
Department of Precision Engineering, Chuo University
- 15:30-15:45 Acoustofluidic manipulation system with an open microfluidic chip [TP1_2_3](#)
Natsumi Hirata and Takeshi Hayakawa
Department of Precision Engineering & Chuo University
- 15:45-16:00 Detection and Quantification of Nanoparticles Using the Vibration-Induced Flow [TP1_2_4](#)
Kanji Kaneko¹, Mamiko Tsugane¹, Taku Sato¹, Yosuke Hasegawa², Takeshi Hayakawa¹, and Hiroaki Suzuki¹
¹Chuo University
²Institute of Industrial Science, The University of Tokyo
- 16:00-16:15 Development of a Microchamber Device for Local Evaluation of Epithelial Cell Barrier Function and Cellular Imaging [TP1_2_5](#)
Ryuya Kida, Mamiko Tsugane, and Hiroaki Suzuki
Graduate school of Science and Engineering, Chuo University
- 16:00-16:15 Performance evaluation of Multi-Parameter Measuring System for Liver Organoids [TP1_2_6](#)
Taisuke Masuda¹, Juntaro Nomaru², Satoshi Amaya¹, Shiro Watanabe¹, Hirotaka Sugiura¹, and Fumihito Arai¹
¹Graduate School of Engineering, The University of Tokyo,
²Faculty of Engineering, The University of Tokyo

Session TP2-2: (Organized Session 6-1)
Intelligent Robot Systems

Room 2

Chairperson: *Kenichi Ohara, Meijo University*

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|-------------|--|
| 14:45-15:00 | <p>Display and Disposal Work Using an Electromagnet Hand and Magnetic Markers TP2_2_1</p> <p><i>Riko Sugiyama¹, Tomohito Takubo², and Atsushi Ueno²</i></p> <p>¹<i>Osaka City University</i></p> <p>²<i>Osaka Metropolitan University</i></p> |
| 15:00-15:15 | <p>Rearrangement planning with multi-functional shelf considering the cost of regrasping products and changing posture of products TP2_2_2</p> <p><i>Takeshi Nakamura¹, Tomohito Takubo², and Atsushi Ueno²</i></p> <p>¹<i>Osaka City University</i></p> <p>²<i>Osaka Metropolitan University</i></p> |
| 15:15-15:30 | <p>Improving the Success Rate of Pose Estimation of Objects by Image Translation for Product Display TP2_2_3</p> <p><i>Kohei Fujita and Tsuyoshi Tasaki</i></p> <p><i>Graduate School of Science and Technology, Meijo University</i></p> |
| 15:30-15:45 | <p>Modularized panel-type IoT device for user intuitive service on desktop environment TP2_2_4</p> <p><i>Kairi Kanada¹, Kazuki Moriya², Masato Iijima², Koji Hayashi², and Kenichi Ohara¹</i></p> <p>¹<i>Department of Mechatronics Engineering, Faculty of Science and Technology, Meijo University</i></p> <p>²<i>Misawa Home Institute of Research and Development Co., Ltd.</i></p> |
| 15:45-16:00 | <p>Welding seam detection between cylinder and plane using point cloud data TP2_2_5</p> <p><i>Ryosuke Kusumoto, Tomohito Takubo, and Tetsuo Tsujioka</i></p> <p><i>Osaka Metropolitan University</i></p> |
| 16:00-16:15 | <p>Intension Reading based Task Outcome Prediction for Operability Improvement of Time-Delayed Teleoperation System TP2_2_6</p> <p><i>Keisuke Fusano, Yaonan Zhu, Jacinto Enrique Colan Zaita, Tadayoshi Aoyama, and Yasuhisa Hasegawa</i></p> <p><i>Department of Micro-Nano Mechanical Science and Engineering, Nagoya University</i></p> |

November 30 (Wed)

Session WA1-1: (Organized Session 1-1)

Advanced Micro-Nano Systems for Biomedical Applications

Room 1

Chairpersons: *Hisataka Maruyama, Nagoya University*

- 9:00-9:30 Keynote Talk 1-1
 Cryoprotectant Agent-free Cell Cryopreservation by Superflash Freezing
 Using Inkjet Cell Printing..... [WA1_1_1](#)
Yoshitake Akiyama
Faculty of Textile Science and Technology, Shinshu University
- 9:30-9:45 Contact Non-Contact Droplets Printing in Fluorocarbon (FC-40) with
 Automated 3D Single Cell Printer [WA1_1_2](#)
*Muhammad Awais Maqbool¹, Shunya Okamoto¹, Takayuki Shibata¹, and
 Moeto Nagai^{1,2}*
¹*Department of Mechanical Engineering, Toyohashi University of
 Technology*
²*Electronics-Inspired Interdisciplinary Research Institute (EIIRIS),
 Toyohashi University of Technology*
- 9:45-10:00 Evaluation of pressure dispersion and limited photosensitization of cell
 membrane perforators with hollow geometry [WA1_1_3](#)
*Kohei Kobayashi¹, Rie Akamatsu², Yuka Okinaka², Kenji Imamura¹, Kirihiro
 Suzuki¹, Koki Takemasa¹, Stephanie Nix³, and Akihiko Taguchi²*
Takashi Kei Saito¹
¹*Akita Prefectural University*
²*Foundation for Biomedical Research and Innovation at Kobe*
³*Iwate Prefectural University*
- 10:00-10:15 High-speed liquid exchange using a 3D printed probe with dual pumps
 [WA1_1_4](#)
*Xu Du¹, Shingo Kaneko², Hisataka Maruyama¹, Hirotaka Sugiura² and
 Fumihito Arai^{1,2}*
¹*Department of Micro-Nano Mechanical Science and Engineering,
 Nagoya University*
²*Department of Mechanical Engineering, The University of Tokyo*

Session WA2-1: (Organized Session 6-2)
Intelligent Robot Systems

Room 2

Chairperson: Takahiro Ikeda, Gifu University

9:15-9:30 Three-Dimensional-Motion Sensations Using a Small Plane-Confined Motion Platform [WA2_1_1](#)
 Takanari Imai, Junya Okada, and Junichi Meguro
 Meijo University

9:30-9:45 Knee joint angle estimation by sequential correction of gyroscope bias [WA2_1_2](#)
 Ayuko Saito¹, Shinichiro Morichi², and Satoru Kizawa³
¹Kogakuin University
²Tokyo Medical University
³National Institute of Technology, Akita College

9:45-10:00 Sensorless grip force estimation of a cable-driven robotic surgical tool based on Gaussian Process Regression [WA2_1_3](#)
 Jacinto Colan and Yasuhisa Hasegawa
 Department of Micro-Nano Mechanical Science and Engineering, Nagoya University

10:00-10:15 Tactile Sensor Based Visual Force Estimation for Force Feedback in Teleoperation [WA2_1_4](#)
 Yaonan Zhu, Shukrullo Nazirjonov, Bingheng Jiang, Jacinto Colan, Tadayoshi Aoyama Yasuhisa Hasegawa
 Department of Micro-Nano Mechanical Science and Engineering, Nagoya University

10:15-10:30 **Break**

Session WA1-2: (Organized Session 1-2)
Advanced Micro-Nano Systems for Biomedical Applications

Room 1

Chairpersons: Hisataka Maruyama, Nagoya University

10:30-11:00 Keynote Talk 1-2
 Measurement of cellular stimulus response based on micro-manipulation techniques using a micro-hand system [WA1_2_1](#)
 Masaru Kojima
 Department of Materials Engineering Science, Osaka University

- 11:00-11:15 State Detection of the Micropipette Injected into Oocyte Using QCR Force Sensor and Image Analysis [WA1_2_2](#)
Yudai Fujimoto, Shiro Watanabe, Hirotaka Sugiura, Bilal Turan, Shingo Kaneko, Satoshi Amaya, Kazusa Otani, and Fumihito Arai
Department of Mechanical Engineering, The University of Tokyo
- 11:15-11:30 Driving of flagellated micro-gel robot by using light-scanning system [WA1_2_3](#)
Hinako Sato¹, Yoshiyuki Yokoyama², Takeshi Hayakawa¹
¹*Department of Precision Engineering, Chuo University*
²*Toyama Industrial Technology Research and Development Center*
- 11:30-11:45 Reconfiguration of modular microgel robot by light irradiation [WA1_2_4](#)
Natsuki Watanabe¹, Yoshiyuki Yokoyama² and Takeshi Hayakawa¹
¹*Department of Precision Mechanics, Chuo University*
²*Toyama Industrial Technology Research and Development Center*
- 11:45-12:00 Glucose/Oxygen Powered Microswimmer with Magnetic Steering [WA1_2_5](#)
Toshiro Yamanaka and Fumihito Arai
Department of Mechanical Engineering, the University of Tokyo

Session WA2-2: (Organized Session 6-3)

Intelligent Robot Systems

Room 2

Chairperson: *Junichi Meguro, Meijo University*

- 10:30-10:45 Improvement of Object Detection and Depth Estimation by 3D Convolution for Autonomous Driving [WA2_2_1](#)
Kotaro Kurake and Tsuyoshi Tasaki
Graduate School of Science and Technology, Meijo University
- 10:45-11:00 Error Trends Analysis in Localization Using 3D Point Clouds With Matching Reliability [WA2_2_2](#)
Yuta Takahashi¹, Tatsuya Minami¹, Yudai Yamazaki², Eijiro Takeuchi³, Yoshiki Ninomiya⁴, Hirotaka Kato¹, and Junichi Meguro¹
¹*Meijo University*
²*MAP IV, Inc.*
³*TIER IV, Inc.*
⁴*Nagoya University*

- 11:00-11:15 Direction Estimation by Using Depth Image for Gesture Interface of AMR [WA2_2_3](#)
Taiyo Aoki, Takahiro Ikeda, Satoshi Ueki, and Hironao Yamada
Department of Mechanical Engineering, Gifu University
- 11:15-11:30 Consideration of Positioning Control Method of AMR with Pointing
 Gesture Recognition and Object Tracking [WA2_2_4](#)
Takahiro Ikeda, Naoki Noda, Satoshi Ueki, and Hironao Yamada
Department of Mechanical Engineering, Gifu University
- 11:30-11:45 Sound Source Localization based on audiovisual information for
 out-of-view objects [WA2_2_5](#)
Usha Regmi, Kaho Yamahira, and Tsuyoshi Tasaki
Graduate School of Science and Technology, Meijo University
- 11:45-12:00 Sound Source Localization in Blind Spots Using Map Images for
 Autonomous Robots [WA2_2_6](#)
Yudai Furukawa and Tsuyoshi Tasaki
Graduate School of Science and Technology, Meijo University
- 12:00-13:00 **Lunch**

Session WP1-1: (Organized Session 1-3)

Advanced Micro-Nano Systems for Biomedical Applications

Room 1

Chairpersons: *Hisataka Maruyama, Nagoya University*

- 13:00-13:15 High-Speed Frequency Detection of QCR Force Sensor Using a PLL
 Circuit [WP1_1_1](#)
Shiro Watanabe, Hirotaka Sugiura, and Fumihito Arai
Department of Mechanical Engineering, Graduate School of Engineering,
The University of Tokyo
- 13:15-13:30 Quantitative evaluation of scleral incision sensation in glaucoma artificial
 surgery [WP1_1_2](#)
Keisuke Miyahara¹, Seiji Omata¹, Toshiro Yamanaka², Kanako Harada²,
Mamoru Mitsuishi², Koichiro Sugimoto³, Takashi Ueta³, Tomoyasu
Shiraya³, Fumiyuki Araki³, Muneyuki Takao³, Makoto Aihara³, Yasuyuki
Morita¹, Fumihito Arai²
¹*Faculty of Advanced Science and Technology, Kumamoto University*
²*Department of Mechanical Engineering, The University of Tokyo*
³*Department of Ophthalmology, The University of Tokyo*

- 13:30-13:45 Contact Detection between Forceps and Retinal Model Using Image Analysis for Ophthalmic Surgery Simulator..... WP1_1_3
Kenta Noda and Hisataka Maruyama
Department of Micro-Nano Mechanical Science and Engineering, Nagoya University
- 13:45-14:00 Estimation of cauterization depth in hydrogel heart model having temperature memory and load measurement functions WP1_1_4
Ryoma Yusaki and Hisataka Maruyama
Department of Micro-Nano Mechanical Science and Engineering, Nagoya University
- 14:00-14:15 Light-controlled microgripper with solid-liquid phase-transition ti WP1_1_5
Hisataka Maruyama
Department of Micro-Nano Mechanical Science and Engineering, Nagoya University

Session WP2-1: (Organized Session 6-4)
Intelligent Robot Systems

Room 2

Chairperson: *Takahiro Ikeda, Gifu University*

- 13:00-13:15 Disorganized Product Detection by using Ordered Window WP2_1_1
Shirai Yuichi and Tsuyoshi Tasaki
Graduate School of Science and Technology, Meijo University
- 13:15-13:30 Development of a Master–Slave Robotic System for Vascular Interventional Surgery..... WP2_1_2
Chaochao Shi¹ and Hidenori Ishihara²
¹*Graduate School of Engineering, Kagawa University*
²*Department of Intelligent Mechanical Systems Engineering, Kagawa University*
- 13:30-13:45 Automatic Puncture Needle Detection by Image Processing Using Deep Learning and CT Values WP2_1_3
Kotaro Mayumi¹, Takayuki Matsuno², Tetsushi Kamegawa³, Ken'ichi Morooka², Takao Hira⁴, and Yuichiro Toda²
¹*Graduate School of Natural Sciences and Technology, Okayama University*
²*Faculty of Natural Science and Technology, Okayama University*
³*Faculty of Interdisciplinary Science and Engineering in Health Systems, Okayama University*

⁴*Faculty of Medical, Dentistry, and Pharmaceutical Sciences, Okayama University*

13:45-14:00 Temporal Convolutional Network-based Gait Event Detection using IMU sensors [WP2_1_4](#)
Yan Guo, Yonatan Hutabarat, Dai Owaki, and Mitsuhiro Hayashibe
Department of Robotics, Graduate School of Engineering, Tohoku University

14:15-14:30 ***Break***

Plenary Talks

Room 1

Chairperson: *Seiichi Hata, Nagoya University*

14:30-15:00 Plenary Talk 4
 Large Diameter SiC Crystal Growth assisted by AI technology [PL4](#)
Toru Ujihara
Nagoya University

15:00- ***Award Ceremony and Closing***